For help screens, select a field and press F1

SECTION I. COURSE SUBMISSION IN	ORMATION	
1. Course: (Enter proposed discipline, numb	er & title here. If changing the number or title of an existing course, give old number	or title in box 4 below.)
Discipline/No:ROB 223 T	itle: Robotics III Hinky AGAD.	uuruuruuruurun on oo
Division Code: <u>TEC</u> Departs	ment Code: INDT Effective Term: 200105 Do no	t publish in Time Schedule t publish in College Catalog
Minor Changes	3. Reason for Submission: This Course is being submitted for: (check New Course Approval (Skip the rest of Section I and go directly to Five-year Syllabus Review No changes to course Major Change(s) Minor Change(s) (If not due for review, submit sections I, II, and Reactivation of Inactive Course Inactivation (Submit Sections I and II only.) Ply. Make proposed changes in Section III, Course Syllabus.) Major Changes (Major changes will be reviewed by Credit hours (credits were: 4)	o Section II.) revised parts of Section III.)
□ Course Discipline/Number (was	Core Elements: (Elements to be added:	90) n.) Approval Form for Distance section.)
5. Rationale for changes: Streamlining the course and adding a s	eparate course in Robotic Simulation.	
SECTION II. COURSE REVIEW INFO		
Department Review (To be completed Will significant new resources be required. Have departments that may be affected. Does the department support approval.)	I by department chair; if recommendation is no, initial and return to preparer red? yes no (If yes, explain	alacka alacka
Print: Gary Schultz Faculty/Prepa	Signature Williams	Date: 1/200/01
Print: Gary Schultz Department Cl	Signature Wary & Hully	Date: [[LG]0]
2. Division Review (To be completed by Will significant new resources be required in the same court of the same completed by What is your estimate of projected enrolling the same commendation Yes No	ision? 🛮 yes 🗀 no (Comment	4/26/01
3. Curriculum Committee Review (Atta		A. I go bio E. Tananananananananananananananananananan
Recommendation Yes No		<u>6.12.01</u>
A Vice President for Instruction and S	tudent Services Approval (Attach additional comments if necessary.)	
Approval Yes No	Vice President's Signature	7 / 3 Date
Log File 3 10/0/ ACS Code Core Elements Approved	Catalog File Date 7100 30 Acce	ss Date <u>7-10 61 120 </u> 35

SECTION III. COURSE SYLLABUS For help screens, select a field and press F1.

A. 1	COURSE DETAILS (discipline # and	title will automatically be entered in a	and 2 below upon saving or previewing)
	Course Discipline & No.: ROB 223		
	sorting, counting, measuring, and palleti	zing. Programmable controllers are used utomated conveyors, vision systems, bar ELE-224 (Programmable Control	obotic workcells. Labs include part recognition, to interface robots with other automated coding, and automated welding. It is llers) before taking this course. This course
4.	Credit Hours: 2	5. Class Capacity: 18 6. C	Course Options:
	If Variable credit, Give Range:to If repeatable for credit, how many times?	(If nonstandard, attach Class Capacity Exception form.)	Distance learning (Attach preliminary distance approval form and Section Handout.) Honors (Complete Part G.) P/NP Grading (Attach rationale.)
7.	Contact Hours per Semester in:	8. Prerequisite(s):	9. Corequisite(s): (limit to 2)
''	Lecture: 15		ROB 222
	Lab: 30 Clinical:	ROB 212	1000 9333
	Experiential: Total Contact Hrs: 45		AREAS CONTRACTOR CONTR
10.	a. Course Purpose: Program Specialty Program Support Nonprogram Specialty Transfer Enrichment Basic Skills	b. Is this course a requirement for a program? Yes (specify the program(s) below) No	c. Indicate schools to which you want Curriculum Services to send syllabus: (If transfer is approved, attach documentation.) EMU UM Other

- **B. MAJOR INSTRUCTIONAL UNITS** A major instructional unit is a grouping of topics that naturally relate to one another. List in order the major instructional units. Add additional numbers as needed.
 - 1. Advanced VAL II and V+ programming
 - 2. Binary Vision Systems
 - 3. Various types of robot I/O control
 - 4. Programmable Controller Interfacing
 - 5. Automated conveyor operation
 - 6. Introduction to Bar coding
 - 7. Introduction to automated welding

D. INSTRUCTIONAL OBJECTIVES AND CORE ELEMENTS SUPPORTED

DIRECTIONS: (These Units should match those listed in Section B.) Use student outcome based language. (Example: The student will develop and support a thesis in an essay.) If the objective is being used to directly support a core element, write the core element number in the box to the right. If needed, additional information on how the core element is to be met and/or assessed for accomplishment can be included under the objective. If desired you may add a section of "overall course objectives" which are not associated with a specific unit. This may be particularly helpful for addressing core elements.

Uni	t Objectives	Core Elements
Unit	#1 Advanced VAL II and V+ programming	
# 1	Students will effectively program and use an emergency safety gate and "no parts" r	outine.
# 2	Students will use the robot to measure and sort parts.	
#3	Students will use whiledo, prompt, reacti, and ifthenelse programming constru	icts.
Unit	#2 Binary Vision System	
#1	Students will check for presence of attributes in parts using pixel count.	
# 2	Students will measure parts using edge detection.	
#3	Students will learn to choose the correct lighting in order to optimize vision perform	nance.
Unit	#3 Various types of I/O control	
#1	Students will learn the different types of Input and Output control used on our robot	s.
# 2	Students will learn to choose appropriate sensors for each robot.	
# 3	Students will learn the difference between PNP and NPN logic.	
Unit	#4 Programmable Logic Controller interfacing	
#1	Students will perform simple "hand shaking" between a PLC and a robot.	
#2	Students will use timers and counters when interfacing.	
# 3	Students will perform various levels of signal conversion between unlike voltages. (ie. 24 VDC to 120 VAC.)	
		an audityyniai neith thair au
		partenane esterbiblication

Unit #5	Automated conveyor operation	
#1	Students will be able to describe the operation of the Bosch automated conveyor.	
#2	Students will write a simple PLC program to sequence the pallets and stops.	
# 3	Students will interface a robot with the conveyor using a PLC.	
Unit #6	Introduction to bar coding	
#1	Students will describe operation of simple UPC codes for bar coding.	
#2	Students will interface a robot, conveyor, and bar code reader for tracking parts.	
Unit #7	Introduction to automated welding	
#1	Students will write basic programs for robotic welding.	
#2	Students will use correct terminology as related to robotic MIG welding.	philadeladurateria de describación de cris.
#3	Students will adjust welding parameters to correct basic welding problems.	

E. INSTRUCTIONAL METHODS AND EVALUATION 1. Instructional Methods: (Check the appropriate boxes and describe as needed.) ☐ Field Trips

☐ Clinica	l Instruction	Team Assignments
Self-Pa	aced Learning	Telecourse
☐ Interne	t Instruction	Video Seminar
	iter Simulations	
On-Site	e Work Experience	Interactive TV
☐ Other		
2. Evaluat	tion Criteria:	Quizzes
Class		Tests
☐ Papers	S	Midterm
☐ Portfo	lio	Final Exam
	ts	Home Work
☐ Repor	ts	Presentations
☐ Clinic	al/Work] Performances
☐ Other		
3. Attenda	ance Requirements: (For Certification or nonev	aluative purposes.)

1. Special	EMENT, FACILITIES, TEXTS, MATERIALS Equipment/Facilities: (Check the appropriate bequipment Robots in TI shop	
☐ LRC	Reserves	Student Competitions
☐ Com	puters	Off-Campus Sites
☐ CD F	ROM	Student Tutors
☐ Field	Trips	Distance Learning Classroom
Other 2. Texts:	(Please indicate if no text is required.)	

Title:	No Text Required		
Author:		Copyright Yr:	atmires exercises
Publisher:		Est. Cost:	
Title:		•	simelinini
Author:		Copyright Yr:	*****
Publisher:		Est Costs	nanarir
Title: Author:			
Publisher:	**************************************		
ruonsner:	10000000000000000000000000000000000000	Est. Cost:	*****
Title:			****
Author:	·	Copyright Yr:	سبسب
Publisher:		Est. Cost:	
Title:			
Author:	***************************************	Copyright Yr:	
Publisher:		Est. Cost:	
Other Text	S:		****
3. Supplies	s: s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil,		MARAN
3. Supplies	s and/or Uniforms Student will have to Own or Acquire for (***************************************
3. Supplies	s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil,	paper, or textbooks.)	
3. Supplies	s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil,	paper, or textbooks.)	
3. Supplies (e.g. calcul	s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil,	paper, or textbooks.)	aminjoha Galakak
3. Supplies (e.g. calcul	s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil, Descriptions ce Materials Students Will Use:	paper, or textbooks.)	
4. Referen (e.g. journa 5. Audio/V	s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil, Descriptions ce Materials Students Will Use:	paper, or textbooks.)	
4. Referen (e.g. journa 5. Audio/V	s and/or Uniforms Student will have to Own or Acquire for eators, uniforms, tools, and software, etc., excluding pen, pencil, Descriptions ce Materials Students Will Use: als, books, manuals, maps, LRC reserves, etc.)	paper, or textbooks.)	
4. Referen (e.g. journa 5. Audio/V	ce Materials Students Will Use: als, books, manuals, maps, LRC reserves, etc.) Visual and Computer Materials Students Will Use: video tapes, slides, audio tapes, software, CDs, etc.)	Cost Estimates	
4. Referen (e.g. journa 5. Audio/V	ce Materials Students Will Use: als, books, manuals, maps, LRC reserves, etc.) Visual and Computer Materials Students Will Use: video tapes, slides, audio tapes, software, CDs, etc.) Title	Cost Estimates	
4. Referen (e.g. journa 5. Audio/V	ce Materials Students Will Use: als, books, manuals, maps, LRC reserves, etc.) Visual and Computer Materials Students Will Use: video tapes, slides, audio tapes, software, CDs, etc.) Title	Cost Estimates	
4. Referen (e.g. journa 5. Audio/V	ce Materials Students Will Use: als, books, manuals, maps, LRC reserves, etc.) Visual and Computer Materials Students Will Use: video tapes, slides, audio tapes, software, CDs, etc.) Title	Cost Estimates	
4. Referen (e.g. journa 5. Audio/V	ce Materials Students Will Use: als, books, manuals, maps, LRC reserves, etc.) Visual and Computer Materials Students Will Use: video tapes, slides, audio tapes, software, CDs, etc.) Title	Cost Estimates	